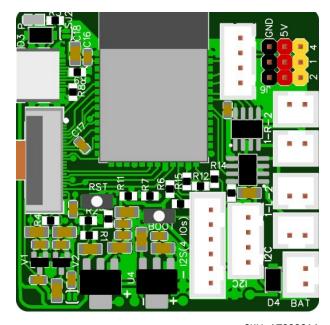


AIOT GMAC

ESP S3 based Development Board for Robots Product Reference Manual



SKU: AT000014 Latest Release: 23 Dec 2023

Description:

The AIOT GMAC ESP32 S3 N4 R2 SoC development board is a powerful platform designed for advanced robotics and IoT applications. It features an ESP32 S3 microcontroller, which combines a dual-core processor with Wi-Fi (2.4 GHz, IEEE 802.11b/g/n) and Bluetooth (BLE 5 LE and Bluetooth® mesh) capabilities, providing robust connectivity and processing power for complex projects.

Key features of this development board include an SD card socket for 1-bit mode data storage, a 4-pin female connector for an I2C OLED display, and an in-built OV2640 2MP camera for visual input. The board is equipped with SR04-US pins (Vcc, 44-Digital IO/I2C, 43-Digital IO/I2C, Gnd) for ultrasonic sensors and dedicated pins for motor control (L1 & L2 on pins 39 and 40, R1 & R2 on pins 41 and 42).

The board supports multiple I2C configurations: a 4-pin I2C connector with Gnd, Vcc, 21-SDA, and 14-SCL, and a 6-pin I2C connector with Gnd, Vcc, 46-LRCK, 45-BLCK, 47-Din & Microphone IN, and 0-Dout for speakers. Power options include a DC jack for 7 to 9V DC, 1A input, an external battery connector for a 2-pin JST male (designed for a 7.4V Li-ion 2-cell battery), and a USB C-type port for power and programming.

The AIOT GMAC ESP32 S3 development board's combination of powerful processing, extensive connectivity, and versatile I/O options makes it an ideal choice for building sophisticated robotic systems and IoT projects.



1. Features

Processor

ESP32-S3-N4 R2 SoC

Dual-core Xtensa® 32-bit LX7 microprocessor, operating at up to 240 MHz.

Memory - 512 KB of internal SRAM, support for external flash and SRAM.

Connectivity:

Wi-Fi: 2.4 GHz, IEEE 802.11b/g/n

Bluetooth: Bluetooth 5 LE, Bluetooth mesh

Security: Hardware encryption (AES, SHA, RSA) and secure boot

Power Management: Ultra-low-power co-processor, various power modes for energy-efficient operation.

Peripheral Interfaces - Onboard & Direct mount

Programmable GPIOs: 10

Memory & Storage: Integrated Memory

SD card socket for the card (1-bit mode)

Digital Interfaces: 4-pin female connector for OLED display (I2C)

Camera: Built-in OV2640 2MP camera
Sensor Interfaces: Ultrasonic Sensor (SR04-US)

[Pins: Vcc, Digital IO/I2C (Pin 44), Digital IO/I2C (Pin 43), Gnd]

Motor Control Pins: L1 & L2 Pins: Pin 39, Pin 40.

R1 & R2 Pins: Pin 41, Pin 42.

12C Interfaces: 4-pin connector [Gnd, Vcc, Pin 21 (SDA), Pin 14 (SCL)]

6-pin connector [Gnd, Vcc, Pin 46 (LRCK), Pin 45 (BLCK), Pin 47 (Din &

Microphone IN), Pin 0 (Dout for Speakers)]

General Purpose Input/Output: Multiple GPIO pins available for various interfaces and connections

Other Interfaces: SPI, I2S, UART

Power Supply: DC Jack: 7 to 9V DC, 1A

Power Consumption: Active Mode (depends on peripherals in use)

Deep Sleep Mode (typically in microampere)
Light Sleep Mode (typically in milliwatt range)

External Battery: 2-pin JST male connector for Li-ion, 2-cell, 7.4V battery

USB Interface: USB C-type for power and programming.

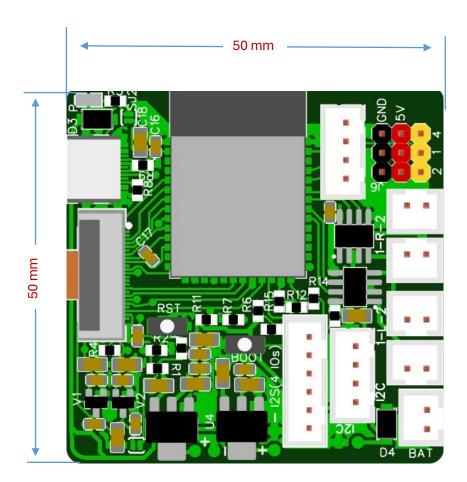
Temperature Range: Typically -40°C to +85°C (refer to the ESP32 S3 N4 R2 SoC datasheet)

Relative Humidity: Typically 10% to 90% non-condensing



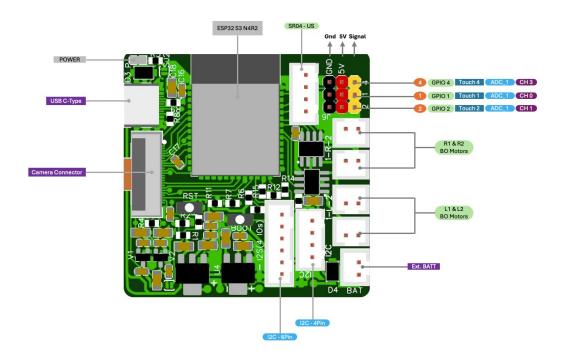
1.1 Mechanical Layout

The AIOT GMAC ESP S3 development board features a compact design with strategically placed connectors and components for easy access and efficient signal routing. Key elements like the ESP32 S3 N4 R2 SoC, power inputs, and peripheral connectors are centrally located for optimal performance. The board includes multiple mounting holes for secure attachment in various enclosures and robotic platforms, and clear labelling ensures easy identification of all connection points. This layout facilitates straightforward integration into IoT and robotic projects.





2. Overview - Pinout Diagram



ESP32 S3 N4 R2 SOC

SD card socket for card - 1-Bit Mode

Camera: In-build, OV2640 2MP Camera

SR04-US Pins: Vcc, 44-Digital IO/I2C, 43-Digital IO/I2C, Gnd

L1 & L2 Pins: 39, 40 R1 & R2 Pins: 41, 42 Wi-Fi: 2.4 GHz, IEEE 802.11b/g/n, Bluetooth: BLE 5 LE and Bluetooth* mesh

I2C Pins (4-pin): Gnd, Vcc, 21-SDA, 14-SCL
I2C Pins (6-pin): Gnd, Vcc, 46-LRCK, 45-BLCK, 47-Din & Microphone IN, 0 - Dout for Speakers

DC JACK - 7 to 9V DC, 1A Ext. BATT - 2 PIN JST MALE - Use Li-ion, 2-Cell, 7.4V, 2 pin only.

USB C-type: For Power and Programming

* Please use the battery supplied by AlTink * No Battery charging option SchoolFor®

SchoolFor®

ESP S3 Development
Board for Robots

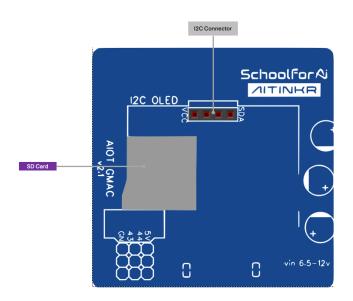
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Update: 21 May 2024

Pinout Diagram (Top)

Documentation: PDF
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Contd..



ESP32 S3 N4 R2 SOC DC JACK - 7 to 9V DC, 1A Ext. BATT - 2 PIN JST MALE - Use Li-ion, 2-Cell, 7.4V, 2 pin only. AIOT GMAC Wi-Fi: 2.4 GHz, IEEE 802.11b/g/n, Bluetooth: BLE 5 LE and Bluetooth® mesh Camera: In-build, OV2640 2MP Camera 1TINKR ESP S3 Development SR04-US Pins: Vcc, 44-Digital IO/I2C, 43-Digital IO/I2C, Gnd I2C Pins (4-pin): Gnd. Vcc. 21-SDA. 14-SCL. Board for Robots USB C-type: For Power and Programming OLED Display: 4-pin Female to plug - I2C I2C Pins (6-pin): Gnd, Vcc, 46-LRCK, 45-BLCK, 47-Din & Microphone IN, 0 - Dout for Speakers Page: 2 of 2 SKU Code: C00034 L1 & L2 Pins: 39, 40 R1 & R2 Pins: 41, 42 Update: 21 May 2024 * Please use the battery supplied by AlTinkr * No Battery charging option I2C Connector (reverse): 1.3" OLED, direct Pinout Diagram (Bottom)

 Pin 2:
 GPIO 2 | Touch2 | ADC_1 | CH 1 | (3-pins - Signal, 5V, Gnd)

 Pin 1:
 GPIO 1 | Touch1 | ADC_1 | CH 0 | (3-pins - Signal, 5V, Gnd)

 Pin 4:
 GPIO 4 | Touch4 | ADC_1 | CH 3 | (3-pins - Signal, 5V, Gnd)

Ultrasonic: SR04-US

BO Motors: R1 & R2: 2 off Right Side Motors - 1 Channel from the motor driver shared between these two

L1 & L2: 2 off Left Side Motors - 1 Channel from the motor driver shared between these two

12C: 4-Pin JST12C: 6-Pin JST

BOOT: To jump to the Microcontroller Boot Mode

RST: Reset the Microcontroller USB: Type-C (Power & Upload)

Ext. BATT: 3 PIN JST MALE - Use Li-ion 2Cell, 7.4V, with in-built BMS only (check the wiring on PCB)